



Elementary question

V , vector space $V \cong \bigoplus V_i$ for V_i irreducible w.r.t. some extra data.

E.g.

$G \curvearrowright V$ repr. $V \cong \bigoplus V_i$, V_i irreducible repr.

How about coherent sheaves?

Similar notion called stability.

\mathcal{F}

\downarrow

(X, ω) X proj.

Def. \mathcal{F} stable if \mathcal{F} does not contain any subsheaf E s.t.

$$\mu(E) > \mu(\mathcal{F}) \quad \left(\mu(\mathcal{F}) = \frac{\int_X c_1(\mathcal{F}) \wedge \omega^{\dim X - 1}}{\text{rk}(\mathcal{F})} \right)$$

Q: $\mathcal{F} \cong \bigoplus \mathcal{F}_i$, \mathcal{F}_i stable?

Ans 1: (DUY / KH)

E v.b.

\downarrow

(X, ω) Kähler

$E \cong \bigoplus E_i$, E_i stable $\iff E$ admits HYM connection

Ans 2: (works for much more objects)

$\forall \mathcal{F}$ pure admits a HN filtration

$0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_{n-1} \subseteq \mathcal{F}_n = \mathcal{F}$ s.t. $\mathcal{F}_i / \mathcal{F}_{i-1}$ is semistable

~> Works on derived Cart of coherent sheaves.

To mimic Ans 2, we need

(i) full subcats $\mathcal{P}(\chi)$ for any $\chi \in \mathbb{R}$ s.t.

$$\text{Hom}_{D^b(X)}(\mathcal{P}(\chi_1), \mathcal{P}(\chi_2)) = 0 \text{ if } \chi_1 < \chi_2 \text{ (} \mathcal{P}(\chi_i) \in \mathcal{P}(X) \text{)}$$

(ii) $\forall E \in D^b(X)$, \exists HN filtration, i.e.

$$0 = E_0 \rightarrow E_1 \rightarrow E_2 \rightarrow \dots \rightarrow E_n = E, \quad E_i \in D^b(X), \quad \phi_{i+1} > \phi_i$$

$\nwarrow \quad \swarrow \quad \nwarrow \quad \swarrow$
 $\mathcal{P}(\phi_1) \quad \mathcal{P}(\phi_2) \quad \mathcal{P}(\phi_{n-1})$

(iii) $\mathcal{P}(\chi)[1] = \mathcal{P}(\chi+1)$

And there is an obvious candidate given by original HN filtration.

① $\forall E \in D^b(X)$, we can filter E by cohomological degree, i.e.

$$0 \rightarrow E^{\leq -n} \rightarrow E^{\leq -n+1} \rightarrow \dots \rightarrow E^{\leq m-1} \rightarrow E^{\leq m} = E \rightarrow 0$$

$\nwarrow \quad \swarrow \quad \nwarrow \quad \swarrow \quad \nwarrow \quad \swarrow$
 $H^n(E) \quad H^{-n+1}(E) \quad H^{-n+2}(E) \quad \dots \quad H^m(E)$

② $H^i(E) \in \text{Coh}(X)$, then we can filter $H^i(E)$ by HN filtration

$$0 \rightarrow E_0^i \rightarrow E_1^i \rightarrow \dots \rightarrow E_{m_i}^i = H^i(E) \rightarrow 0$$

$\nwarrow \quad \swarrow \quad \nwarrow \quad \swarrow$
 $\text{HN}(E) \quad \text{HN}(E)$

as. $0 \rightarrow E_j^i \xrightarrow{\text{incl.}} E_{j+1}^i \rightarrow \text{HN}^{j+1}(E) \rightarrow 0$ is SES.

③ Construct map $E^{\leq -n} \rightarrow E_0^{-n+1}$

(we don't need to start from $E^{\leq -n}$ as $E^{\leq -n} = H^{-n}(E)$ by definition of truncation)

We got two exact triangles:

$$\begin{array}{ccccc} E_i^{-n+1} & \longrightarrow & E^{\leq -n}[i] & \longrightarrow & Q_i^{-n+1}[i] & \cong & \text{Con}(E_i^{-n+1} \rightarrow E^{\leq -n}[i]) \\ \downarrow & & \parallel & & \downarrow & & \\ E_{i+1}^{-n+1} & \longrightarrow & E^{\leq -n}[i] & \longrightarrow & Q_{i+1}^{-n+1}[i] & \cong & \text{Con}(E_{i+1}^{-n+1} \rightarrow E^{\leq -n}[i]) \end{array}$$

And by octahedral axiom:

$$\begin{array}{ccccc} E^{\leq -n}[i] & \longrightarrow & Q_i^{-n+1}[i] & \longrightarrow & E_i^{-n+1}[i] \\ & \searrow & \downarrow & & \downarrow \\ & & Q_{i+1}^{-n+1}[i] & \longrightarrow & E_{i+1}^{-n+1}[i] \\ & & & \searrow & \downarrow \\ & & & & \widetilde{Q}^{-n+1, i}[i] \end{array}$$

We find comm. diagram

$$\begin{array}{ccccc} Q_i^{-n+1}[i] & \longrightarrow & Q_{i+1}^{-n+1}[i] & \longrightarrow & \widetilde{Q}^{-n+1, i}[i] \\ \downarrow & & \downarrow & & \downarrow_{i+1} \text{ (by uniqueness of Con)} \\ E_i^{-n+1}[i] & \longrightarrow & E_{i+1}^{-n+1}[i] & \longrightarrow & H^{-n+1}_{-n+1}(E)[i] \end{array}$$

Note that when $i = m - n + 1$, $Q_{m-n+1}^{-n+1} \cong E^{\leq -n+1}$ (again by uniqueness of Con)

$\Rightarrow E^{\leq -n} \rightarrow Q_0^{-n+1} \rightarrow Q_1^{-n+1} \rightarrow \dots \rightarrow Q_{m-n+1}^{-n+1} \rightarrow E^{\leq -n+1}$
is our desired map.

④ define suitable map $\text{Coh}(X) \rightarrow [0, 1]$

Again we use the standard slope stability

$$E \rightarrow \mu(E) = \frac{\deg(E)}{\text{rk}(E)} \text{ but in a slightly different coordinate}$$

$$\leadsto E \rightarrow \deg(E) + i \text{rk}(E) \in \mathbb{C} \\ = |h(E)| e^{i2\pi\theta(E)}$$

$$\text{Fact: } \theta(E) > \theta(F) \iff \mu(E) > \mu(F)$$

And for $\forall E, E' \in \text{Coh}(X)$, we have

$$\text{Hom}(E[1], E') = \text{Ext}^{-1}(E, E') = 0$$

However, a big disadvantage of slope stability is that when $\dim_{\mathbb{C}} X \geq 2$, we can not talk about stability of torsion sheaves, i.e. pick $E \xrightarrow{\pi} X$ s.t. $\text{rk}(E) = 0 = c_1(E)$

Then $\mu(E)$ & $\theta(E)$ are both not defined.

So in addition we need

$$(iv) \quad K_0(D^b(X)) = K_0(X) \xrightarrow{\text{Ch}} \Lambda \xrightarrow{\text{additive homo. } Z} \mathbb{C} \\ \forall E \in \mathcal{D}(\phi), Z(\text{Ch}(E)) \in \mathbb{R}_{>0} e^{2\pi i \phi}$$

And a technical requirement to avoid wild stability condition
(I don't have any understanding on it)

(V)

$$\inf \left\{ \frac{\|Z(\text{Ch}(E))\|}{\|\text{Ch}(E)\|} : 0 \neq E \in \mathcal{P}(\phi) \right\} > 0$$

(actually it is a pretty strong property.)

When X is curve, $K_0(X) \xrightarrow{\text{Ch}} \Lambda \cong \mathbb{Z}^{\text{rk}} \oplus \mathbb{Z}^{\text{deg}}$

$$\Rightarrow \|Z(\text{Ch}(E))\| = |\text{rk}(E)|^2 + |\text{deg}(E)|^2 = \|\text{Ch}(E)\|$$

$$\Rightarrow \inf \frac{\|Z(\text{Ch}(E))\|}{\|\text{Ch}(E)\|} = 1 > 0$$

\Rightarrow slope stability define a Bridgeland stability when X is curve.

Thm. (Toda) When $\dim_{\mathbb{C}}(X) \geq 2$, we can't choose

$\mathcal{P}(\phi)$ to be $\text{Coh}(X)$.

Then we need to do some filling (maybe discuss in the future)

Space of stability condition

The space of stability condition $\text{Stab}(X)$ is consisted of (\mathcal{P}, Z)

and the topology is defined as follow:

For $\sigma_1 = (\mathcal{P}_1, Z_1)$, $\sigma_2 = (\mathcal{P}_2, Z_2)$

$$|\sigma_1 - \sigma_2| = \sup_{E \in \mathcal{D}(X), E \neq 0} \left\{ |\phi_{\sigma_1}^+(E) - \phi_{\sigma_2}^+(E)|, |\phi_{\sigma_1}^-(E) - \phi_{\sigma_2}^-(E)|, \|Z_1 - Z_2\|_g \right\}$$

here we filter E by \mathcal{P}_1 & \mathcal{P}_2

$$0 = E_0 \xrightarrow{r_1} E_1 \rightarrow \dots \rightarrow E_{n-1} \rightarrow E_n = E$$

\downarrow \downarrow
 $\mathcal{P}_1(\phi_{\sigma_1}^1)$ $\mathcal{P}_1(\phi_{\sigma_1}^n)$

$$0 = E'_0 \rightarrow E'_1 \rightarrow \dots \rightarrow E'_{m-1} \rightarrow E_m = E$$

$$\phi_{g_1}^+(E) = \phi_{g_1}^n, \quad \phi_{g_1}^-(E) = \phi_{g_1}^1, \quad \text{same for } g_2$$

And we fix a metric g on $\text{Hom}(\Lambda, \mathbb{C})$.

This is the coarsest topology to make functions

$$(\mathfrak{g}, z) \rightarrow z \quad \text{continuous}$$

$$\& \forall E \in \mathcal{D}(X), \quad (\mathfrak{g}, z) \rightarrow \phi^+(E)$$

$$(\mathfrak{g}, z) \rightarrow \phi^-(E) \quad \text{continuous.}$$

Thm. (Bridgeland)

$$\text{The map } (\mathfrak{g}, z) \in \text{Stab}(X), \quad (\mathfrak{g}, z) \rightarrow z$$

is a local homeomorphism, i.e. $\text{Stab}(X)$ admits a cplx mfd

structure with dimension $= \dim_{\mathbb{C}} \Lambda \otimes \mathbb{C}$